

Momento angular orbital $\hat{L} = \hat{R} \times \hat{P}$

- Usando la representación $\{|\vec{r}\rangle\}$

$$\hat{R} \rightarrow \vec{r} \quad \hat{P} \rightarrow -i\hbar \vec{\nabla} \quad \int |\psi|^2 dV = 1$$

En coordenadas esféricas $\psi(\vec{r}) = \psi(r, \theta, \varphi)$

$$L_z = -i\hbar \frac{\partial}{\partial \varphi}$$

$$L^2 = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right)$$

$$\begin{aligned} L^2 |l m\rangle &= \hbar^2 l(l+1) |l m\rangle \xrightarrow{\{|\vec{r}\rangle\}} - \left[\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right] \psi(r, \theta, \varphi) = l(l+1) \psi(r, \theta, \varphi) \\ L_z |l m\rangle &= \hbar m |l m\rangle \quad -i \frac{\partial}{\partial \varphi} \psi(r, \theta, \varphi) = m \psi(r, \theta, \varphi) \end{aligned}$$

- Para l fijo los valores permitidos de m son $m = -l, -l+1, \dots, l-1, l$

- Como r no aparece en los operadores diferenciales al hacer separación de variables $\psi(r, \theta, \varphi) = f(r) Y_l^m(\theta, \varphi)$ obtenemos

$$L^2 Y_l^m(\theta, \varphi) = \hbar^2 l(l+1) Y_l^m(\theta, \varphi)$$

$$L_z Y_l^m(\theta, \varphi) = \hbar m Y_l^m(\theta, \varphi)$$

(sin dependencia angular)

$$\rightarrow -i \frac{\partial}{\partial \varphi} Y_l^m(\theta, \varphi) = m Y_l^m(\theta, \varphi)$$

Usando separación de variables

$$Y_l^m(\theta, \varphi) = F_l^m(\theta) \Phi(\varphi)$$

no ponemos constante
pues se la achacamos a
la $F_l^m(\theta)$

$$\Rightarrow -i \Phi'(\varphi) = m \Phi(\varphi) \Rightarrow \Phi(\varphi) = e^{im\varphi}$$

$$\therefore Y_l^m(\theta, \varphi) = F_l^m(\theta) e^{im\varphi}$$

Veamos que para el momento angular orbital, l debe ser entero positivo.

(i.e. en este caso no puede tener un valor semi-entero).

Para que $Y_l^m(\theta, \varphi)$ sea univaluada.

$$Y_l^m(\theta, \varphi) = Y_l^m(\theta, \varphi + 2\pi)$$

$$\Rightarrow F_l^m(\theta) e^{im\varphi} = F_l^m(\theta) e^{im(\varphi + 2\pi)}$$

$$\Rightarrow 1 = e^{im2\pi}$$

$$\Rightarrow m \text{ es entero}$$

$$\Rightarrow l \text{ es entero,}$$

Una forma de obtener las soluciones sin usar la ecuación diferencial espantosa,

$$-\left[\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right] Y_l^m(\theta, \varphi) = l(l+1) Y_l^m(\theta, \varphi) \leftarrow$$

es utilizar la teoría de momento angular que ya tenemos.

Por ejemplo, sabemos que $L_+ Y_l^{m=l} = 0$
 $\hat{L}_+ |l, m=l\rangle = 0$

$$L_x = i\hbar \left(\sin \varphi \frac{\partial}{\partial \theta} + \frac{\cos \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} \right)$$

$$L_y = i\hbar \left(-\cos \varphi \frac{\partial}{\partial \theta} + \frac{\sin \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} \right)$$

$$L_+ = L_x + iL_y$$

$$= \hbar \left[i \sin \varphi \frac{\partial}{\partial \theta} + i \frac{\cos \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} + \cos \varphi \frac{\partial}{\partial \theta} + i \frac{\sin \varphi}{\tan \theta} \frac{\partial}{\partial \varphi} \right]$$

$$L_+ = \hbar e^{i\varphi} \left[\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right]$$

$$L_- = \hbar e^{-i\varphi} \left[-\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right]$$

Si resolvemos la ecuación

$$L_+ Y_l^{m=l}(\theta, \varphi) = 0$$

para obtener Y_l^l , podemos usar L_- para obtener $Y_l^m(\theta, \varphi)$ para los $m < l$.

$$L_+ Y_l^{m=l}(\theta, \varphi) = 0 \Rightarrow \cancel{\hbar e^{i\varphi}} \left[\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right] F_l^m(\theta) e^{il\varphi} = 0$$

$$\left[\frac{\partial}{\partial \theta} - l \cot \theta \right] F_l^m(\theta) = 0$$

$$\frac{1}{F_l^m(\theta)} \frac{dF_l^m(\theta)}{d\theta} = l \frac{\cos \theta}{\sin \theta}$$

$$\Rightarrow \frac{d}{d\theta} \ln(F_l^m(\theta)) = l \frac{d}{d\theta} \ln(\sin \theta)$$

integrando respecto a θ

$$\ln F_l^m(\theta) = l \ln(\sin \theta) + C$$

$$F_l^m(\theta) = \underbrace{e^C}_N \sin^l(\theta) = N \sin^l \theta$$

$$\therefore Y_l^m(\theta, \varphi) = F_l^m(\theta) \Phi(\varphi) = N \sin^l \theta e^{im\varphi}$$

Vamos a escoger N de tal manera que

$$\int_0^{2\pi} \int_0^\pi |Y_l^m(\theta, \varphi)|^2 \sin \theta d\theta d\varphi = 1$$

para que

$$\begin{aligned} \int |\Psi(\vec{r})|^2 dV &= \iiint_{\infty}^0 |f(r)|^2 |Y_l^m(\theta, \varphi)|^2 r^2 \sin \theta d\theta d\varphi dr \\ &= \left[\int_0^\infty |f(r)|^2 r^2 dr \right] \left[\int_0^{2\pi} \int_0^\pi |Y_l^m(\theta, \varphi)|^2 \sin \theta d\theta d\varphi \right] \end{aligned}$$

$l = 0$	$l = 1$	$l = 2$
$Y_0^0 = \sqrt{\frac{1}{4\pi}}$	$Y_1^{\pm 1} = \pm \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\varphi}$ $Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta$	$Y_2^{\pm 2} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{\pm 2i\varphi}$ $Y_2^{\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\varphi}$ $Y_2^0 = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$

La expresión general para cualquier valor de l y m está dada por

$$Y_l^m(\theta, \varphi) = (-1)^m \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} P_l^m(\cos \theta) e^{im\varphi}, \quad m \geq 0;$$

$$Y_l^{-m}(\theta, \varphi) = (-1)^m Y_l^m(\theta, \varphi)^*;$$

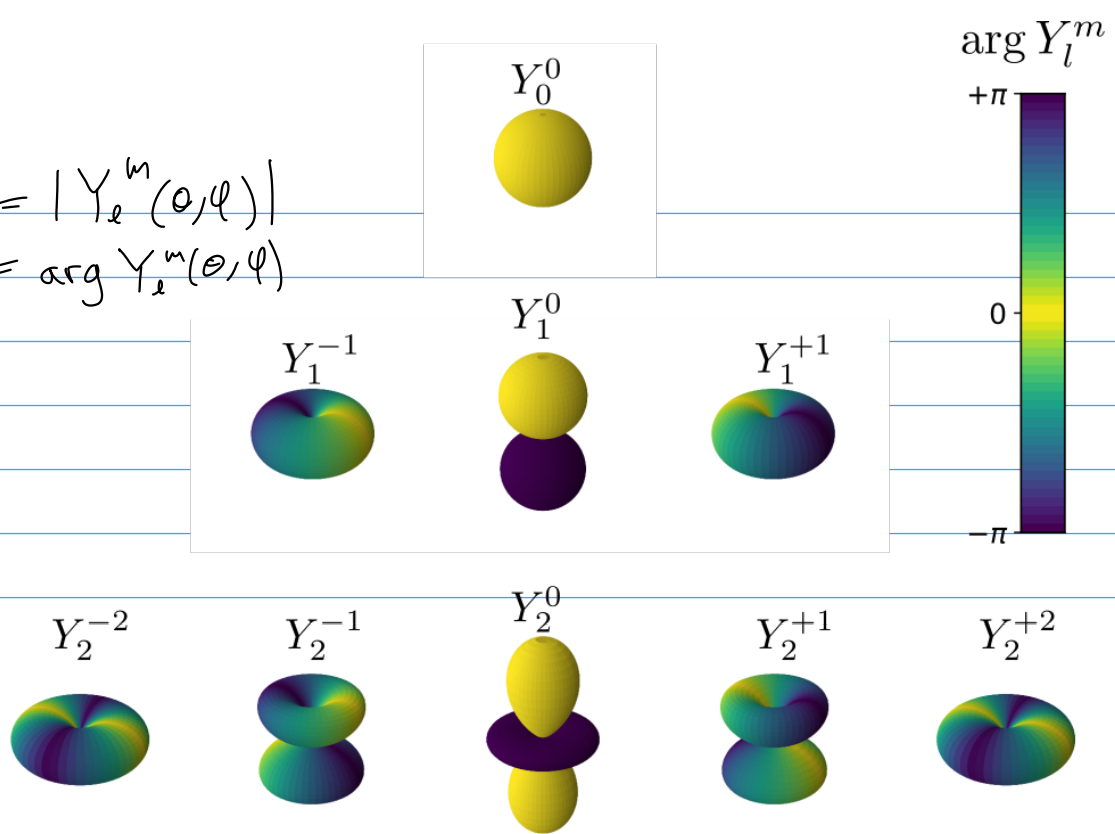
$$P_l^m(x) = (1-x^2)^{|m|/2} \frac{d^{|m|}}{dx^{|m|}} P_l(x);$$

$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l.$$

Aquí, a $P_l^m(x)$ se le conoce como polinomio asociado de Legendre.

$$r = |Y_l^m(\theta, \varphi)|$$

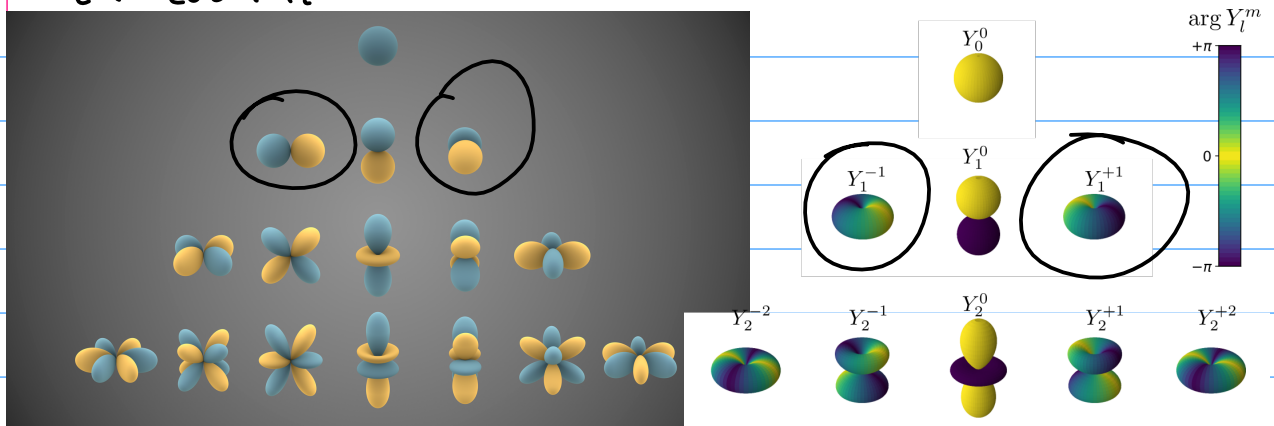
$$\text{color} = \arg Y_l^m(\theta, \varphi)$$



HOW STANDARDS PROLIFERATE:
(SEE: A/C CHARGERS, CHARACTER ENCODINGS, INSTANT MESSAGING, ETC.)



Convención real, no se usa tanto en cuántica.



$$\begin{pmatrix} -1 & -i & 1 \\ & \cdot & \\ & +i & \end{pmatrix} + \begin{pmatrix} -1 & -i & 1 \\ & \cdot & \\ & +i & \end{pmatrix} = \infty$$

$$\begin{pmatrix} -1 & -i & 1 \\ & \cdot & \\ & +i & \end{pmatrix} - \begin{pmatrix} -1 & -i & 1 \\ & \cdot & \\ & -i & \end{pmatrix} = 8$$

$$\begin{pmatrix} -1 & -i & 1 \\ & \cdot & \\ & +i & \end{pmatrix} \cdot \begin{pmatrix} -1 & i & 1 \\ & \cdot & \\ & -i & \end{pmatrix} = e^{im\varphi}$$